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Linear discriminant analysis for the small sample size problem: an overview

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Abstract Dimensionality reduction is an important aspect in the pattern classification literature, and linear discriminant analysis (LDA) is one of the most widely studied dimensionality reduction technique. The application of variants of LDA technique for solving small sample size (SSS) problem can be found in many research areas e.g. face recognition, bioinformatics, text recognition, etc. The improvement of the performance of variants of LDA technique has great potential in various fields of research. In this paper, we present an overview of these methods. We covered the type, characteristics and taxonomy of these methods which can overcome SSS problem. We have also highlighted some important datasets and software/ packages.

Keywords Linear discriminant analysis (LDA) - Small sample size problem · Variants of LDA · Types · Datasets · Packages

1 Introduction

In a pattern classification (or recognition) system, an object (or pattern) which is characterized in terms of a feature vector is assigned a class label from a finite number of predefined classes. For this, the pattern classifier is trained using a set of training vectors (called the training dataset)

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and its performance is evaluated by classifying the feature vectors from the test dataset (which is normally different from the training dataset). In many pattern classification problems, the dimensionality of the feature vector is very large. It is therefore imperative to reduce the dimensionality of the feature space for improving the robustness (or generalization capability) and computational complexity of the pattern classifier. Different methods used for dimensionality reduction can be grouped into two categories: feature selection methods and feature extraction methods. Feature selection methods retain only few useful features and discards less important (or low ranked) features. Feature extraction methods reduce the dimensionality by constructing a few features from the large number of original features through their linear (or non-linear) combination. There are two popular feature extraction techniques reported in the literature for reducing the dimensionality of the feature space. These are principal component analysis (PCA) and linear discriminant analysis (LDA). PCA is an unsupervised technique, while LDA is a supervised technique. In general, LDA outperforms PCA in terms of classification performance.

The LDA technique finds an orientation W that transforms high dimensional feature vectors belonging to different classes to a lower dimensional feature space such that the projected feature vectors of a class on this lower dimensional space are well separated from the feature vectors of other classes. If the dimensionality reduction is from d-dimensional (\mathbb{R}^d) space to h-dimensional (\mathbb{R}^h)
space (where $h \leq d$) then the size of the orientation matrix space (where $h \langle d \rangle$, then the size of the orientation matrix **W** is $\mathbb{R}^{d \times h}$; i.e., it has h column vectors. The orientation matrix **W** is obtained by maximizing the Eisher's criterion matrix W is obtained by maximizing the Fisher's criterion function; in other words by the eigenvalue decomposition (EVD) of $\mathbf{S}_{W}^{-1}\mathbf{S}_{B}$, where $\mathbf{S}_{W} \in \mathbb{R}^{d \times d}$ is within-class scatter

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matrix and $S_B \in \mathbb{R}^{d \times d}$ is between-class scatter matrix. For a c-class problem, the value of h will be min($c - 1$, d). If the dimensionality d is very large compared to the number of training vectors n , then S_W becomes singular and the evaluation of eigenvalues and eigenvectors of $S_W^{-1}S_B$ becomes impossible. This drawback is considered to be the main problem of LDA and is commonly known as the small sample size (SSS) problem [\[15](#page-10-0)].

Over last several years, the discriminant analysis research is centered on developing algorithms that can solve SSS problem. In this overview, we focus on the LDA based techniques that can solve SSS problems. For brevity, we refer these techniques as LDA-SSS techniques. We provide taxonomy, characteristics and usage of these LDA-SSS techniques. The objective is to make the readers aware of the benefits and importance of these methods in the pattern classification applications. In addition, we have also highlighted some existing software/packages or programs useful for the LDA-SSS problem and mentioned about some of the commonly used datasets. Since these packages are not available from one place, we have developed Matlab functions for various LDA-SSS methods and it can be downloaded from our website [\(https://maxwell.ict.griffith.edu.au/](https://maxwell.ict.griffith.edu.au/spl/) [spl/](https://maxwell.ict.griffith.edu.au/spl/) or [http://www.staff.usp.ac.fj/](http://www.staff.usp.ac.fj/~sharma_al/index.htm) \sim sharma_al/index.htm).

2 Linear discriminant analysis

As mentioned earlier, the LDA technique finds an orientation W that reduces high dimensional feature vectors belonging to different classes to a lower dimensional feature space such that the projected feature vectors of a class on this lower dimensional space are well separated from the feature vectors of other classes. This technique is illustrated in Fig. 1, where two-dimensional feature vectors are reduced to one-dimensional feature vector. The feature vectors belong to three different classes namely C1, C2 and C3. An orientation is to be found where the projected feature vectors (on a line) of a class are to be maximally separated from the feature vectors of other classes. It can be observed that orientation \hat{W} does not separate projected feature vectors quite well. However, rotating the line further to orientation W and projecting two-dimensional feature vectors on this orientation separate the projected feature vectors of a class with other classes. Thus, the orientation W is a better selection than the orientation \tilde{W} . The value of W can be obtained by maximizing the Fisher's criterion function $J(W)$. This criterion function depends on three factors: orientation W, within-class scatter matrix (S_w) and between-class scatter matrix (S_B) . If the dimensionality reduction is from d -dimensional space to h-dimensional space, then the size of orientation

Fig. 1 An illustration of LDA technique

matrix **W** is $d \times h$, and **W** has $h \le \min (c -1, d)$ (where c is the number of classes) column vectors known as the basis vectors.

To define LDA explicitly, let us consider a multi-class pattern classification problem with c classes. Let $X = \{x_1, x_2, ..., x_n\}$ denotes *n* training samples (or feature vectors) in a d-dimensional space having class labels $\Omega = {\omega_1, \omega_2, ..., \omega_n}$, where $\omega \in \{1, 2, ..., c\}$ and c is the number of classes. The set X can be subdivided into c subsets X_1 , X_2 ,..., X_c where X_j belongs to class j and consists of n_i number of samples such that:

$$
n=\sum_{j=1}^c n_j
$$

and $X_i \subset X$ and $X_1 \cup X_2 \cup \ldots \cup X_c = X$.

If μ_i is the centroid of X_i and μ is the centroid of X, then the total scatter matrix $S_T \in \mathbb{R}^{d \times d}$, within-class scatter matrix $\mathbf{S}_W \in \mathbb{R}^{d \times d}$ and between-class scatter matrix \mathbf{S}_B $\mathbb{R}^{d \times d}$ are defined as [\[43](#page-10-0), [46](#page-10-0)]

$$
S_T = \sum_{x \in \mathbf{X}} (\mathbf{x} - \boldsymbol{\mu}) (\mathbf{x} - \boldsymbol{\mu})^T,
$$

\n
$$
S_W = \sum_{j=1}^c \sum_{\mathbf{x} \in \mathbf{X}_j} (\mathbf{x} - \boldsymbol{\mu}_j) (\mathbf{x} - \boldsymbol{\mu}_j)^T
$$

\nand
$$
S_B = \sum_{j=1}^c n_j (\boldsymbol{\mu}_j - \boldsymbol{\mu}) (\boldsymbol{\mu}_j - \boldsymbol{\mu})^T.
$$

where $S_T = S_B + S_W$. The Fisher's criterion as a function of W can be given as

$$
J(\mathbf{W}) = \left| \mathbf{W}^{\mathrm{T}} \mathbf{S}_{B} \mathbf{W} \right| / \left| \mathbf{W}^{\mathrm{T}} \mathbf{S}_{W} \mathbf{W} \right|
$$

where $|\cdot|$ is the determinant. The orientation matrix **W** is the solution of eigenvalue problem

 $\mathbf{S}_W^{-1} \mathbf{S}_B \mathbf{w}_i = \lambda_i \mathbf{w}_i$

where w_i (for $i = 1...h$) are the column vectors of W that correspond to the largest eigenvalues (λ_i) . There are several other criterion function also used which provide equivalent results [[15\]](#page-10-0).

In the conventional LDA technique, S_W needs to be nonsingular. However, in the SSS case, this scatter matrix becomes singular. To overcome this problem, various LDA-SSS methods have been proposed in the literature. The next section discusses variants of LDA technique.

3 Variants of LDA technique (LDA-SSS) for solving SSS problem

In LDA-SSS, there are four informative spaces namely, null space of S_W (S_W^{null}), range space of S_W (S_W^{range}), range space of S_B (S_B^{range}) and null space of S_B (S_B^{null}). The computations of these spaces are very expensive and different methods use different strategies to tackle the computational problem. A popular way of reducing the computational complexity is by doing a preprocessing step. The preprocessing step is described as follows. It is known that the null space of S_T does not contain any discriminant information $[21]$ $[21]$. Therefore, the dimensionality can be reduced from d -dimensional space to r_t -dimensional space (where r_t is the rank of S_T) by applying PCA as a pre-processing step [\[15](#page-10-0), [44](#page-10-0)]. The range space of S_T matrix, $U_1 \in \mathbb{R}^{d \times r_i}$, is used as a transformation matrix. In the reduced dimensional space the scatter matrices is given by: reduced dimensional space the scatter matrices is given by: $\mathbf{S}_w = \mathbf{U}_1^{\mathrm{T}} \mathbf{S}_w \mathbf{U}_1$ and $\mathbf{S}_b = \mathbf{U}_1^{\mathrm{T}} \mathbf{S}_b \mathbf{U}_1$. After this procedure $\mathbf{S}_w \in \mathbb{R}^{r_t \times r_t}$ and $\mathbf{S}_b \in \mathbb{R}^{r_t \times r_t}$ are reduced dimensional within-class scatter matrix and reduced dimensional between-class scatter matrix, respectively.

These four informative spaces are illustrated in Fig. 2 after carrying out the preprocessing step¹; i.e., the data is first transformed to the range space of S_T . Let the transformed spaces are depicted by $S_w^{null}, S_w^{range}, S_b^{null}$ and S_b^{range} . In Fig. 2, the symbols r_w , r_b and r_t are the rank of matrices \mathbf{S}_W , \mathbf{S}_B and \mathbf{S}_T , respectively. If the samples in training set are linearly independent then $r_t = r_w + r_b$ and their values will be $r_t = n - 1$, $r_w = n - c$ and $r_b = c - 1$. Further, the dimensionality of spaces S_{w}^{null} and S_{b}^{range} will be identical. Similarly, the dimensionality of spaces S_{w}^{range} and S_b^{null} will be identical.

These four individual spaces contain significant discriminant information useful for classification. This is illustrated in

Fig. 2 An illustration of all the four spaces of LDA when SSS problem exist

Fig. 3 Average classification accuracy over k -fold cross-validation $(k = 5)$ using spaces $S_w^{null}, S_w^{range}, S_b^{range}$ and S_b^{null}

Fig. $3²$ where the classification performance obtained by the individual spaces is shown. Among these spaces, S_b^{null} is the least effective space, but it still contains some discriminant information. Different combinations of these spaces are used in the literature for finding the orientation matrix W. The following four combinations have been used most in the literature: (1) \mathbf{S}_{W}^{range} and \mathbf{S}_{B}^{range} , (2) \mathbf{S}_{W}^{null} and \mathbf{S}_{B}^{range} , (3) $\mathbf{S}_{W}^{null}, \mathbf{S}_{W}^{range}$ and \mathbf{S}_{B}^{range} , and (4) $\mathbf{S}_{W}^{null}, \mathbf{S}_{W}^{range}, \mathbf{S}_{B}^{range}$ and \mathbf{S}_{B}^{null} . Based on these distinct combinations, we categorize the following LDA-SSS techniques into one of the four categories: null LDA (NLDA) [\[9](#page-10-0)], PCA $+$ NLDA [\[21](#page-10-0)], orthogonal LDA (OLDA) [\[62](#page-11-0)], uncorrelated LDA (ULDA) [\[63](#page-11-0)], QR-NLDA

¹ These four spaces can also be represented in Fig. 2 without performing a preprocessing step. In that case, r_t in the figure will be replaced by the dimensionality d and the size of the spaces will change accordingly.

² For this experiment, first we project the original feature vectors onto the range space of S_T matrix as a pre-processing step. Then all the spaces are utilized individually to do dimensionality reduction and to classify a test feature vector, the nearest neighbor classifier is used. To obtain performance in terms of average classification accuracy, kfold cross-validation process has been applied, where $k = 5$. The details of the datasets have been given later in Sect. 10.1.

[\[10](#page-10-0)], fast NLDA (FNLDA) [\[49](#page-11-0)], discriminant common vector LDA (CLDA) [[8\]](#page-10-0), direct LDA (DLDA) [[67\]](#page-11-0), kernel DLDA (KDLDA) [[28](#page-10-0)], parameterized DLDA (PDLDA) [[56](#page-11-0)], improved DLDA (IDLDA) [\[36](#page-10-0)], pseudoinverse LDA (PIL-DA) [[59](#page-11-0)], fast PILDA (FPILDA) [[27](#page-10-0)], improved PILDA (I-PILDA) [[34\]](#page-10-0), LDA/QR [\[64\]](#page-11-0), approximate LDA (ALDA) [[35](#page-10-0)], $PCA + LDA [5, 57]$ $PCA + LDA [5, 57]$, regularized $LDA (RLDA) [14, 29, 30, 30]$ $LDA (RLDA) [14, 29, 30, 30]$ [68–70](#page-11-0)], eigenfeature regularization (EFR) [\[22\]](#page-10-0), extrapolation of scatter matrices (ELDA) [[47\]](#page-11-0), maximum uncertainty LDA (MLDA) [\[58\]](#page-11-0), penalized LDA (PLDA) [[20](#page-10-0)], two-stage LDA (TSLDA) [\[50](#page-11-0)], maximum margin criterion LDA (MMC-LDA) [\[26\]](#page-10-0) and improved RLDA (IRLDA) [[54\]](#page-11-0).

Table 1 Classification accuracies (in percentage) of several LDA based techniques

Techniques	ORL	AR	FERET	Average
DLDA	89.5	80.8	92.9	87.7
OLDA	91.5	80.8	97.1	89.8
$PCA + LDA$	86.0	83.4	95.7	88.4
RLDA	91.5	75.4	97.3	88.1
MLDA	92.0	76.2	97.8	88.7
EFR	92.3	81.8	97.7	90.6
TSLDA	92.3	87.7	97.7	92.6
PILDA	91.0	82.1	96.1	89.7
FPILDA	91.0	82.1	96.1	89.7
NLDA	91.5	80.8	97.1	89.8
ULDA	88.3	89.6	97.1	91.7
QR-NLDA	91.5	80.8	97.1	89.8
FNLDA	91.5	80.8	97.1	89.8
CLDA	91.5	80.8	97.1	89.8
IPILDA	87.5	87.9	97.1	90.8
ELDA	90.8	87.0	97.1	91.6
ALDA	91.3	72.1	96.7	86.7
IDLDA	91.5	72.7	96.9	87
IRLDA	92.0	81.9	97.7	90.5

Fig. 4 Average classification accuracies (in %) of several LDA based techniques over three datasets

The classification accuracies of several of these methods have been computed on three datasets (for description of datasets please refer to Section Datasets) and twofold cross-validation results are shown in Table 1 and their average classification performance over 3 datasets is shown in Fig. 4. The nearest neighbor classifier has been used for classification purpose.

Table 2 shows the categorization (or taxonomy) of these LDA-SSS methods. It should be noted that different LDA-SSS techniques use different combinations of spaces and the performance of a given LDA-SSS technique depends on the particular combination it uses. In addition, it depends in what manner these spaces are combined. Four categories are depicted (types 1–4). Most of the techniques fall under the first three categories. The fourth category (type-4) has not been fully explored in the literature. Figure 5 depicts average classification performance of all types over 3 face recognition datasets. Further characterization of these categories is discussed in the following subsections.

Table 2 Taxonomy for LDA based algorithms used for solving SSS problem

TYPE-1 $S_{W}^{range} + S_{B}^{range}$	TYPE-2 $S_{W}^{null} + S_{B}^{range}$	TYPE-3 $S_{W}^{null} + S_{W}^{range} + S_{B}^{range}$	TYPE-4 all spaces
DLDA	NLDA	RLDA	TSLDA
KDLDA.	$PCA + NLDA$	ALDA	
PDLDA	OLDA	EFR	
PILDA	ULDA	ELDA	
FPILDA	OR-NLDA	MLDA	
LDA/OR	FNLDA	IDLDA	
PCA + LDA	CLDA	PLDA	
MMC-LDA	IPILDA	IRLDA	

Fig. 5 Average classification accuracy of best three methods of a particular type over three face recognition datasets (ORL, AR and FERET). (For Type 4 only 1 method has been selected). It can be observed that as the type increases the average performance improves. However, the improvement is based on how effectively the spaces are utilized in the computation of the orientation matrix

3.1 Type-1 based techniques

LDA-SSS techniques of type-1 category employ S_{w}^{range} and S_b^{range} spaces to compute the orientation matrix W and therefore discard S_w^{null} and S_b^{null} . This could, however, affect the classification performance adversely as the discarded spaces have significant discrimination information. Some of these methods compute W in two stages (e.g. DLDA) and some in one stage (e.g. PILDA). In general, type-1 methods are economical in computing the orientation matrix. However, their performances are not as good as that of other types of methods.

3.2 Type-2 based techniques

Techniques in this category utilize S_{w}^{null} and S_{b}^{range} spaces and discard the other two spaces. It has seen empirically (in Fig. [3](#page-2-0)) that for most of the datasets, S_{w}^{null} contains more discriminant information than other spaces for classification performance. Therefore, employing S_w^{null} in a discriminant technique would enable to compute better orientation matrix W compared to Type-1 based techniques. However, since these techniques discard the other two spaces, its classification performance is suboptimal. The theory of many of these techniques are different, but they produce almost similar performance in terms of classification accuracy. The computational complexity of some of the type-2 methods is high. Nonetheless, they show encouraging classification performances.

3.3 Type-3 based techniques

To compute the orientation matrix W , the techniques in this category utilize the three spaces; i.e., S_w^{null} , S_w^{range} and S_b^{range} . All the three spaces contain significant discrimination information and since Type-3 techniques employ more spaces than the previous two categories (Type-1 and Type-2), intuitively it would give a better classification performance. However, different strategies of combining these three spaces would result in different level of generalization capability. These methods require higher computational complexity. But produce encouraging performance if all the three spaces are effectively utilized.

3.4 Type-4 based techniques

It has been seen (in Fig. [3\)](#page-2-0) that though S_b^{null} is the least effective space, it still contains some discrimination information useful for classification. If S_b^{null} can also be used appropriately with the other spaces for the computation of orientation matrix W, then classification performance can be further improved. So far very few techniques have been explored in this category. The computational complexity in this category is very high but they can produce good classification performance provided that all the spaces are utilized effectively.

This section illustrated the four informative spaces for solving SSS problem. Based on the utilization of different spaces, various techniques can be categorized into four types. However, it is possible that performance of techniques in a given type can vary. This is because various techniques (of a particular type) apply the spaces for computing the orientation matrix in different ways. Therefore, how effectively spaces are utilized can vary the performance of techniques (this can be observed from Table [1](#page-3-0) where techniques of a particular type vary in performances). Nonetheless, in general utilizing spaces effectively would improve the performance (as shown in Fig. [5](#page-3-0) for best three methods).

4 Review of LDA based techniques for solving SSS problem

In this section, we review some of the common LDA based techniques for solving SSS problem. In a SSS problem, the within-class scatter matrix S_W becomes singular and its inverse computation becomes impossible. In order to overcome this problem, approximation of inverse of S_W matrix has been used to compute the orientation matrix W. There are various techniques to compute this inverse in the literature in different ways. Here we review some of the techniques:

4.1 Fisherface (PCA $+$ LDA) technique

In Fisherface method, d-dimensional features are firstly reduced to h-dimensional feature space by the application of PCA and then LDA is applied to further reduce features to k dimensions. There are several criteria for determining the value of h [[5,](#page-9-0) [57\]](#page-11-0). One way is to select $h = n - c$ as the rank of S_W is $n - c$ [[5\]](#page-9-0). The advantage of this method is that it overcome SSS problem. However, the drawback is that some discriminant information has been lost in the PCA application to $n - c$ dimensional space.

4.2 Direct LDA

Direct LDA (DLDA) is an important dimensionality reduction technique for solving small sample size problem [\[67](#page-11-0)]. In the DLDA method, the dimensionality is reduced in two stages. In the first stage, a transformation matrix is computed to transform the training samples to the range space of S_B ; i.e.,

 $\mathbf{U}_r^{\mathrm{T}}\mathbf{S}_B\mathbf{U}_r = A_B^2.$ or $A_B^{-1} \mathbf{U}_r^{\mathrm{T}} \mathbf{S}_B \mathbf{U}_r A_B^{-1} = \mathbf{I}_{b \times b}$.

where U_r corresponds to the range space of S_B (i.e., Λ_B) and $b = rank(S_B)$.

In the second stage, the dimensionality of this transformed samples is further transformed by some regulating matrices; i.e., the transformation matrix $U_r \Lambda_B^{-1}$ is used to transform S_W matrix as

$$
\hat{\mathbf{S}}_W = \mathbf{\Lambda}_B^{-1} \mathbf{U}_r^{\mathrm{T}} \mathbf{S}_W \mathbf{U}_r \mathbf{\Lambda}_B^{-1} = \mathbf{F} \Sigma_w^2 \mathbf{F}^{\mathrm{T}}
$$

or $\Sigma_w^{-1} \mathbf{F}^{\mathrm{T}} \mathbf{\Lambda}_B^{-1} \mathbf{U}_r^{\mathrm{T}} \mathbf{S}_W \mathbf{U}_r \mathbf{\Lambda}_B^{-1} \mathbf{F} \Sigma_w^{-1} = \mathbf{I}_{b \times b}.$

Therefore, the orientation matrix of DLDA technique can be given as $\mathbf{W} = \mathbf{U}_r \mathbf{\Lambda}_B^{-1} \mathbf{F} \Sigma_w^{-1}$. The benefit of DLDA technique is that it does not require PCA transformations to reduce the dimensionality as required by other techniques like Fisherface (or PCA $+$ LDA) technique [[5,](#page-9-0) [57\]](#page-11-0).

4.3 Regularized LDA

When the dimensionality of feature space is very large compared to the number of training samples available, then the S_W matrix becomes singular. To overcome this singularity problem in the regularized LDA (RLDA) method, a small perturbation to the S_W matrix has been added [[12,](#page-10-0) [14,](#page-10-0) [69](#page-11-0)]. This makes the S_W matrix non-singular. The regularization can be applied as follows:

$$
(\mathbf{S}_W + \delta \mathbf{I})^{-1} \mathbf{S}_B \mathbf{w}_i = \lambda_i \mathbf{w}_i
$$

where $\delta > 0$ is a perturbation term or regularization parameter. The addition of δ in the regularized method helps to incorporate both the null space and range space of S_W . However, the drawback is that there is no direct way of evaluating the parameter as it requires heuristic approaches to evaluate it and a poor choice of δ can degrade the generalization performance of the method. The parameter δ has been added just to perform the inverse operation feasible and it has no physical meaning.

4.4 Null LDA technique

In the null LDA (NLDA) technique $[9]$ $[9]$, the h column vectors of the orientation $\mathbf{W} = [\mathbf{w}_1, \mathbf{w}_2, ..., \mathbf{w}_h]$ are taken to be in the null space of the within-class scatter matrix S_W ; i.e., $\mathbf{w}_i^T \mathbf{S}_W \mathbf{w}_i = 0$ for $i = 1...h$. In addition, these column vectors have to satisfy the condition $w_i^T S_B w_i \neq 0$. for $i = 1...h$.

Since the dimensionality of the null space of S_W is $d - (n - c)$, we will have $d - (n - c)$ linearly independent vectors satisfying the two above mentioned conditions. Since $d - (n - c)$ is greater than h, Chen et al. [[9\]](#page-10-0)

have used eigen analysis of S_B matrix to select h leading eigenvectors from these $d - (n - c)$ vectors to form the orientation matrix W . Thus, in the null space method W is found by maximizing $|\mathbf{W}^{\mathrm{T}}\mathbf{S}_{B}\mathbf{W}|$ subject to the constraint $|\mathbf{W}^{\mathrm{T}}\mathbf{S}_W\mathbf{W}| = 0$, i.e.,

$$
\mathbf{W} = \arg \max_{\left|\mathbf{W}^T \mathbf{S}_W \mathbf{W}\right| = 0} \left|\mathbf{W}^T \mathbf{S}_B \mathbf{W}\right|
$$

The null LDA technique finds the orientation W in two stages. In the first stage, it computes W such that $S_WW = 0$: i.e., data is projected on the null space of S_W and throws the range space of S_W . Then in the second stage it finds W that satisfies $S_B W \neq 0$ and maximizes $|W^T S_B W|$. The second stage is commonly implemented through the PCA method applied on S_B . When the dimensionality d of the original feature space is very large in comparison to sample size n , the evaluation of null space becomes nearly impossible as the eigenvalue decomposition of such a large $d \times d$ matrix will lead to serious computational problems. This is a major problem. There are two main techniques in this respect suggested in the literature for computing the orientation W. In the first technique, a pre-processing step is introduced where the PCA technique is applied to reduce the dimensionality from d to $n-1$ by removing the null space of S_T . In the reduced $n - 1$ dimensional space it is possible to compute the null space of S_W . This pre-processing step is then followed by the two steps of the null space LDA method [\[21](#page-10-0)]. In the second technique, no pre-processing is necessary but the required null space of S_W is computed in the first stage by first finding the range space of S_W , then projecting the data onto this range space followed by subtracting it from the original data. After this step, the PCA method is applied to carry out the second stage. It can be seen that in both the techniques range space of S_W was thrown which could have some discriminant information for classification.

4.5 Orthogonal LDA

Orthogonal LDA (OLDA) method [\[62](#page-11-0)] has shown to be equivalent to the null LDA method under a mild condition; i.e., when the training vectors are linearly independent [\[65](#page-11-0)]. In his method, the orientation matrix W is obtained by simultaneously diagonalizing scatter matrices. Therefore, a matrix A_1 . can be found which diagonalizes all scatter matrices; i.e.,

$$
\mathbf{A}_1^{\mathrm{T}}\mathbf{S}_{\mathrm{B}}\mathbf{A}_1\!=\!\Sigma_{\mathrm{B}}, \mathbf{A}_1^{\mathrm{T}}\mathbf{S}_{\mathrm{W}}\mathbf{A}_1\!=\!\Sigma_{\mathrm{W}} \text{ and } \mathbf{A}_1^{\mathrm{T}}\mathbf{S}_T\mathbf{A}_1\!=\!\mathbf{I}_T,
$$

where $\mathbf{A}_1 = \mathbf{U}_1 \mathbf{\Sigma}_T^{-1} \mathbf{P}$, \mathbf{U}_1 is range space of \mathbf{S}_T , $\mathbf{\Sigma}_T$ is eigenvalues of S_T and $\Sigma_T^{-1} \mathbf{U}_1^T \mathbf{H}_B = \mathbf{P} \Sigma \mathbf{Q}^T$ ($S_B = \mathbf{H}_B \mathbf{H}_B^T$). The orientation matrix W can be found by orthogonalizing matrix A_1 ; i.e., $A_1 = QR$, where $W = Q$.

In this method, the dimensionality is reduced from \mathbb{R}^d to \mathbb{R}^{c-1} . The computational complexity of OLDA method is
better than null IDA method and is estimated to be better than null LDA method and is estimated to be $14dn^2 + 4dnc + 2dc^2$ flops (where c is the number of classes).

4.6 QR-NLDA

Chu and Thye [\[10](#page-10-0)] proposed a new implementation of null LDA method by doing QR decomposition. This is faster method than OLDA. Their approach requires approximately $4dn^2 + 2dnc$ computations.

4.7 Fast NLDA

Fast NLDA (FNLDA) method [[49\]](#page-11-0) is an alternative method of NLDA. It assumes that the training vectors are linearly independent. In this method, the orientation matrix is obtained by using the relation $\mathbf{W} = \mathbf{S}_T^+ \mathbf{S}_B \mathbf{Y}$ where Y is a random matrix of rank $c - 1$. This method is so far the fastest method of performing null LDA operation. The fast computation is achieved by using random matrix multiplication with scatter matrices. The computational complexity of FNLDA is $dn^2 + 2dnc$.

4.8 Pseudoinverse method

In the pseudoinverse LDA (PILDA) method [[59\]](#page-11-0), the inverse of within-class scatter matrix S_W is estimated by its pseudoinverse and then the conventional eigenvalue problem is solved to compute the orientation matrix W. In this method, a pre-processing step is used where feature vectors are projected on the range space of S_T to reduce the computational complexity [[21\]](#page-10-0). After the pre-processing step, the reduced dimensional within-class scatter matrix S_w is decomposed as

$$
\hat{\mathbf{S}}_{w} = \mathbf{U}_{w} \mathbf{D}_{w}^{2} \mathbf{U}_{w}^{T}, \quad \text{where}
$$
\n
$$
\mathbf{U}_{w} \in \mathbb{R}^{t \times t}, \mathbf{D}_{w} \in \mathbb{R}^{t \times t}, \ t = rank(\mathbf{S}_{T})
$$
\n
$$
\mathbf{D}_{w} = \begin{bmatrix} \mathbf{\Lambda}_{w} & 0\\ 0 & 0 \end{bmatrix} \text{ and } \mathbf{\Lambda}_{w} \in \mathbb{R}^{w \times w} \text{ (}w \text{ is the rank of } \mathbf{S}_{w} \text{ such that } w < t \text{).}
$$

Let the eigenvectors corresponding to the range space of $\hat{\mathbf{S}}_{w}$ is \mathbf{U}_{wr} and the eigenvectors corresponding to the null space of \hat{S}_w is U_{wn} , i.e., $U_w = [U_{wr}, U_{wn}]$, then the pseudoinverse of S_W can be expressed as

$$
\hat{\mathbf{S}}_{w}^{+}=\mathbf{U}_{wr}\mathbf{\Lambda}_{w}^{-2}\mathbf{U}_{wr}^{T}
$$

The orientation matrix W can now be computed by solving the following conventional eigenvalue problem

$$
\hat{\mathbf{S}}_{w}^{+}\hat{\mathbf{S}}_{b}\mathbf{w}_{i}=\lambda_{i}\mathbf{w}_{i}
$$

where $\hat{\mathbf{S}}_b$ is the between-class scatter matrix in the reduced space. It can be observed that the null space of within-class scatter matrix is discard which would sacrifice some discriminant information.

4.9 Eigenfeature regularization

In eignefeature regularization (EFR) method [[22\]](#page-10-0), S_W is regularized by extrapolating its eigenvalues in its null space. The lagging eigenvalues of S_W is considered as noisy or unreliable which are replaced by an estimation function. Since the extrapolation has been done by an estimation function, it cannot be guaranteed to be optimal in dimensionality reduction.

4.10 Extrapolation LDA

In extrapolation LDA (ELDA) method [\[47](#page-11-0)], the null space of S_W matrix is regularized by extrapolating eigenvalues of S_W using exponential fitting function. This method utilizes range space information and null space information of S_W matrix.

4.11 Maximum uncertainty LDA

The maximum uncertainty LDA (MLDA) method is based on maximum entropy covariance selection approach that overcomes singularity and instability of S_W matrix ([\[58](#page-11-0)]). The MLDA is constructed by replace S_W with its estimate in the Fisher criterion function. This is computed by updating less reliable eigenvalues of S_W .

4.12 Two stage LDA

The two stage LDA (TSLDA) method [[50\]](#page-11-0) exploits all the four informative spaces of scatter matrices. These spaces are included in two separate discriminant analyses in parallel. In the first analysis, null space of S_W and range space of S_B are retained. In the second analysis, range space of S_W and null space of S_B are retained. It has been shown that all four spaces contain some discriminant information which is useful for classification.

5 Applications of the LDA-SSS techniques

In many applications the number of features or dimensionality is much larger than the number of training samples. In these applications, LDA-SSS techniques have been successfully applied. Some of the applications of LDA-SSS techniques are described as follows:

Table 3 Description of datasets

Table 3 continued

5.1 Face recognition

Face recognition system comprises of two main steps: feature extraction (including face detection) and face recognition [[42,](#page-10-0) [70](#page-11-0)]. In feature extraction step, an image of a face (of size $m \times n$) is normally represented by the illumination levels of $m \times n$ pixels (giving a feature vector of dimensionality $d = mn$ and in the recognition step an unknown face image is identified/verified. Several LDA-SSS techniques have been applied for this application (e.g. [\[57](#page-11-0), [68](#page-11-0), [69\]](#page-11-0).

5.2 Cancer classification

The DNA microarray data for cancer classification consists of large number of genes (dimensions) compared to the number of tissue samples or feature vectors. The high dimensionality of the feature space degrades the generalization performance of the classifier and increases its computational complexity. This situation, however, can be overcome by first reducing the dimensionality of feature space, followed by classification in the lower-dimensional feature space. Different methods used for dimensionality reduction can be grouped into two categories: feature selection methods and feature extraction methods. Feature selection methods (e.g. [[11,](#page-10-0) [16,](#page-10-0) [17,](#page-10-0) [31](#page-10-0), [48](#page-11-0), [51–53](#page-11-0)]) retain only a few useful features and discard others. Feature extraction methods construct a few features from the large number of original features through their linear (or nonlinear) combination. A number of papers have been reported for the cancer classification task using the microarray data [[13,](#page-10-0) [25,](#page-10-0) [26](#page-10-0), [33](#page-10-0), [45\]](#page-10-0).

5.3 Text document classification

In the text document classification, a free text document is categorized to a pre-defined category based on its contents [\[1](#page-9-0)]. The text document is a collection of words. To represent a given text document as a feature vector, a finite dictionary of words is chosen and frequencies of these words (e.g. monogram, bigram etc.) are used as features. Dimensionality reduction and classification techniques are applied for the categorization of a document. The LDA-SSS techniques have also been applied to text document classification (e.g. [\[62](#page-11-0), [65\]](#page-11-0).

6 Datasets

In this section we cover some of the commonly used datasets for LDA related methods. Three types of datasets have been depicted. These are face recognition data, DNA microarray gene expression data and text data. The description of datasets is given in Table $3³$ $3³$.

7 Packages

In this section we list some of the packages available. This is shown in Table [4](#page-9-0). We have also developed in our laboratory a LDA-SSS package (written in Matlab), which provides the Matlab functions for computing S_{w}^{null} , S_{w}^{range} , S_b^{range} and S_b^{null} , and implementation of several LDA-SSS techniques such as DLDA, PILDA, FPILDA, PCA $+$ LDA, NLDA, OLDA, ULDA, QR-NLDA, FNLDA, CLDA, IPI-LDA, ALDA, EFR, ELDA, MLDA, IDLDA and TSLDA.

8 Conclusion

In this paper, we reviewed LDA-SSS algorithms for dimensionality reduction. Some of these algorithms

 $\frac{3}{3}$ For more datasets on face see Ralph Gross [\[19\]](#page-10-0), Zhao et al. [[70](#page-11-0)] and <http://www.face-rec.org/databases/>. For bio-medical data see Kent Ridge Bio-medical Repository ([http://datam.i2r.a-star.edu.sg/datasets/](http://datam.i2r.a-star.edu.sg/datasets/krbd/) [krbd/](http://datam.i2r.a-star.edu.sg/datasets/krbd/)).

Table 4 Packages

provide the-state-of-the-art performance in many applications. We discuss and categorize LDA-SSS algorithms into four distinct categories based on the combination of spaces of scatter matrices. We have also highlighted some datasets and software/packages useful to investigate the SSS problem. The LDA-SSS package written in our laboratory has been made available.

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